Birla Institute of Technology and Science, Pilani<br/>Semester I Session: 2017-2018<br/>CHE F414 Transport Phenomena<br/>Comprehensive Test (Close Book + Open Book)Date: 09/12/2017Maximum Marks: 120Weightage: 40 %Duration: 3 hours

### Close Book (Time: 2 hrs)

**Q 1** Consider a non-porous catalyst pellet of radius  $r_0$  suspended in a stagnant solution containing reactant *A*. At the surface of the catalyst pellet, an irreversible first order reaction is taking place  $A \rightarrow B$ . The rate of reaction is equal to the rate constant multiplied by the concentration of A at the surface. The concentration of *A* in the bulk solution far from the catalyst surface (at  $r = R_0$ ) is C<sub>0</sub>. The concentration of *A* is very low in the mixture containing *B* and the other components in solution. The system is at constant temperature and pressure and operates at steady state.

- (a) Derive an expression for molar concentration.
- (b) Derive an expression for the radial molar flux.

[5]

**Q 2** a) An incompressible fluid, maintained at a constant temperature, is flowing radially between two concentric porous spheres with inner and outer radii  $\kappa R$  and R, respectively. Simplify the equation of continuity and the equation of motion to obtain the following expression for differential modified pressure [P(r) - P(R)]:

$$P(r) - P(R) = \frac{1}{2} \rho \left[ v_r(R) \right]^2 \left[ 1 - \left( \frac{R}{r} \right)^4 \right]$$

Newtonian fluid.

b) Repeat the above exercise for two concentric cylinders with inner and outer radii  $\kappa R$  and R, respectively and obtain an expression for differential modified pressure [P(r) - P(R)]. [3+3]

**Q 3** An open circular tank 8 m in diameter contains ethanol at 22 °C exposed to the atmosphere in such a manner that the liquid is covered with a stagnant air film estimated to be 5 mm thick. The concentration of ethanol beyond the stagnant film is negligible. The vapor pressure of ethanol at 22 °C is 30 mm Hg. If ethanol is worth Rs 50/kg, what is the value of the loss of ethanol from this tank in Rs/day? The specific gravity of benzene is 0.791. The diffusivity of ethanol in air is  $0.115 \text{ cm}^2/\text{s}$ . Find out concentration of ethanol in the film at a distance of 2.5 mm from the liquid layer. **[5]** 

**Q4** Consider the steady-state, laminar flow of a fluid of constant density p and viscosity  $\mu$  in a vertical tube of length *L* and radius *R*. The liquid flows downward under the influence of a pressure difference and gravity. We specify that the tube length be very large with respect to the tube radius, so that "end effects" will be unimportant throughout most of the tube; that is, we can ignore the fact that at the tube entrance and exit the flow will not necessarily be parallel to the tube wall. Derive the expression for velocity distribution, maximum velocity, average velocity and mass flow rate considering the slip boundary condition at the wall as described below.

$$v_z(R) = -\beta \tau_{rz}(R)$$
, where  $\beta$  is a positive constant.

**Q.5** Consider an incompressible isothermal fluid in laminar flow between two concentric spheres, whose inner and outer wetted surfaces have radii of  $\kappa R$  and R, respectively. The inner and outer spheres are rotating at constant angular velocities  $\Omega_i$  and  $\Omega_o$ , respectively. The spheres rotate slowly enough that the creeping flow assumption is valid. a) Determine the steady-state velocity distribution in the fluid (for small values of  $\Omega_i$  and  $\Omega_o$ ). b) Find the torques on the two spheres required to maintain the flow of a

 $\begin{bmatrix} \mathbf{a} \end{bmatrix}$ 

[6]

 $\left[\frac{\partial \rho}{\partial t} + (\nabla \cdot \rho \mathbf{v}) = 0\right]$ 

Cartesian coordinates (x, y, z):

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x} \left( \rho v_x \right) + \frac{\partial}{\partial y} \left( \rho v_y \right) + \frac{\partial}{\partial z} \left( \rho v_z \right) = 0 \tag{B.4-1}$$

Cylindrical coordinates  $(r, \theta, z)$ :

$$\frac{\partial \rho}{\partial t} + \frac{1}{r} \frac{\partial}{\partial r} \left( \rho r v_r \right) + \frac{1}{r} \frac{\partial}{\partial \theta} \left( \rho v_\theta \right) + \frac{\partial}{\partial z} \left( \rho v_z \right) = 0 \tag{B.4-2}$$

Spherical coordinates  $(r, \theta, \phi)$ :

$$\frac{\partial \rho}{\partial t} + \frac{1}{r^2} \frac{\partial}{\partial r} (\rho r^2 v_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\rho v_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} (\rho v_\phi) = 0$$
(B.4-3)

<sup>a</sup> When the fluid is assumed to have constant mass density  $\rho$ , the equation simplifies to  $(\nabla \cdot \mathbf{v}) = 0$ .

# §B.6 EQUATION OF MOTION FOR A NEWTONIAN FLUID WITH CONSTANT $\rho$ AND $\mu$

$$[\rho D \mathbf{v} / Dt = -\nabla p + \mu \nabla^2 \mathbf{v} + \rho \mathbf{g}]$$

 $\frac{Cartesian\ coordinates\ (x, y, z):}{\rho\left(\frac{\partial v_x}{\partial t} + v_x\frac{\partial v_x}{\partial x} + v_y\frac{\partial v_x}{\partial y} + v_z\frac{\partial v_x}{\partial z}\right) = -\frac{\partial p}{\partial x} + \mu\left[\frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} + \frac{\partial^2 v_x}{\partial z^2}\right] + \rho g_x \quad (B.6-1)}{\rho\left(\frac{\partial v_y}{\partial t} + v_x\frac{\partial v_y}{\partial x} + v_y\frac{\partial v_y}{\partial y} + v_z\frac{\partial v_y}{\partial z}\right) = -\frac{\partial p}{\partial y} + \mu\left[\frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} + \frac{\partial^2 v_y}{\partial z^2}\right] + \rho g_y \quad (B.6-2)}{\rho\left(\frac{\partial v_z}{\partial t} + v_x\frac{\partial v_z}{\partial x} + v_y\frac{\partial v_z}{\partial y} + v_z\frac{\partial v_z}{\partial z}\right) = -\frac{\partial p}{\partial z} + \mu\left[\frac{\partial^2 v_z}{\partial x^2} + \frac{\partial^2 v_z}{\partial y^2} + \frac{\partial^2 v_z}{\partial z^2}\right] + \rho g_z \quad (B.6-3)$ 

Cylindrical coordinates  $(r, \theta, z)$ :

$$\rho\left(\frac{\partial v_r}{\partial t} + v_r\frac{\partial v_r}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_r}{\partial \theta} + v_z\frac{\partial v_r}{\partial z} - \frac{v_\theta^2}{r}\right) = -\frac{\partial p}{\partial r} + \mu\left[\frac{\partial}{\partial r}\left(\frac{1}{r}\frac{\partial}{\partial r}\left(rv_r\right)\right) + \frac{1}{r^2}\frac{\partial^2 v_r}{\partial \theta^2} + \frac{\partial^2 v_r}{\partial z^2} - \frac{2}{r^2}\frac{\partial v_\theta}{\partial \theta}\right] + \rho g_r \tag{B.6-4}$$

$$\rho\left(\frac{\partial v_{\theta}}{\partial t} + v_{r}\frac{\partial v_{\theta}}{\partial r} + \frac{v_{\theta}}{r}\frac{\partial v_{\theta}}{\partial \theta} + v_{z}\frac{\partial v_{\theta}}{\partial z} + \frac{v_{r}v_{\theta}}{r}\right) = -\frac{1}{r}\frac{\partial p}{\partial \theta} + \mu\left[\frac{\partial}{\partial r}\left(\frac{1}{r}\frac{\partial}{\partial r}\left(rv_{\theta}\right)\right) + \frac{1}{r^{2}}\frac{\partial^{2}v_{\theta}}{\partial \theta^{2}} + \frac{\partial^{2}v_{\theta}}{\partial z^{2}} + \frac{2}{r^{2}}\frac{\partial v_{r}}{\partial \theta}\right] + \rho g_{\theta}$$
(B.6-5)

$$\rho\left(\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z}\right) = -\frac{\partial p}{\partial z} + \mu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r}\right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2}\right] + \rho g_z \tag{B.6-6}$$

Spherical coordinates  $(r, \theta, \phi)$ :

$$\begin{split} \rho \bigg( \frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{v_\theta^2 + v_\phi^2}{r} \bigg) &= -\frac{\partial p}{\partial r} \\ &+ \mu \bigg[ \frac{1}{r^2} \frac{\partial^2}{\partial r^2} (r^2 v_r) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \bigg( \sin \theta \frac{\partial v_r}{\partial \theta} \bigg) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_r}{\partial \phi^2} \bigg] + \rho g_r \\ \rho \bigg( \frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\theta}{\partial \phi} + \frac{v_r v_\theta - v_\phi^2 \cot \theta}{r} \bigg) &= -\frac{1}{r} \frac{\partial p}{\partial \theta} \\ &+ \mu \bigg[ \frac{1}{r^2} \frac{\partial}{\partial r} \bigg( r^2 \frac{\partial v_\theta}{\partial r} \bigg) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \bigg( \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) \bigg) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_\theta}{\partial \phi^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} - \frac{2 \cot \theta}{r^2 \sin \theta} \frac{\partial v_\phi}{\partial \phi} \bigg] + \rho g_\theta \\ \rho \bigg( \frac{\partial v_\phi}{\partial t} + v_r \frac{\partial v_\phi}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\phi}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} + \frac{v_\phi v_r + v_\theta v_\phi \cot \theta}{r} \bigg) = -\frac{1}{r \sin \theta} \frac{\partial p}{\partial \phi} \\ &+ \mu \bigg[ \frac{1}{r^2} \frac{\partial}{\partial r} \bigg( r^2 \frac{\partial v_\phi}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} + \frac{v_\phi v_r + v_\theta v_\phi \cot \theta}{r} \bigg) = -\frac{1}{r \sin \theta} \frac{\partial^2 v_\phi}{\partial \phi^2} + \frac{2}{r^2 \sin \theta} \frac{\partial v_r}{\partial \phi} + \frac{2 \cot \theta}{r^2 \sin \theta} \frac{\partial v_\theta}{\partial \phi} \bigg] + \rho g_\theta \\ &+ \mu \bigg[ \frac{1}{r^2} \frac{\partial}{\partial r} \bigg( r^2 \frac{\partial v_\phi}{\partial r} \bigg) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \bigg( \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\phi \sin \theta) \bigg) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_\phi}{\partial \phi^2} + \frac{2}{r^2 \sin \theta} \frac{\partial v_r}{\partial \phi} + \frac{2 \cot \theta}{r^2 \sin \theta} \frac{\partial v_\theta}{\partial \phi} \bigg] + \rho g_\theta \\ &+ \mu \bigg[ \frac{1}{r^2} \frac{\partial}{\partial r} \bigg( r^2 \frac{\partial v_\phi}{\partial r} \bigg) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \bigg( \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\phi \sin \theta) \bigg) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_\phi}{\partial \phi^2} + \frac{2}{r^2 \sin \theta} \frac{\partial v_r}{\partial \phi} + \frac{2 \cot \theta}{r^2 \sin \theta} \frac{\partial v_\theta}{\partial \phi} \bigg] + \rho g_\theta \\ &+ \mu \bigg[ \frac{1}{r^2} \frac{\partial}{\partial r} \bigg( r^2 \frac{\partial v_\phi}{\partial r} \bigg) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \bigg( \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\phi \sin \theta) \bigg) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_\phi}{\partial \phi^2} + \frac{2}{r^2 \sin \theta} \frac{\partial v_r}{\partial \phi} + \frac{2 \cot \theta}{r^2 \sin \theta} \frac{\partial v_\theta}{\partial \phi} \bigg] + \rho g_\theta \\ &+ \mu \bigg[ \frac{1}{r^2 \partial r} \bigg( r^2 \frac{\partial v_\phi}{\partial r} \bigg) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \bigg( \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\phi \sin \theta) \bigg) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_\phi}{\partial \phi^2} + \frac{2}{r^2 \sin \theta} \frac{\partial v_r}{\partial \phi} + \frac{2}{r^2 \sin \theta} \frac{\partial v_\theta}{\partial \phi} \bigg] + \rho g_\theta \\ &+ \frac{1}{r^2 \sin^2 \theta} \bigg[ \frac{\partial v_e}{\partial \phi} \bigg] + \frac{1}{r^2 \partial \theta} \bigg[ \frac{\partial v_e}{\partial \phi} \bigg] + \frac{1}{r^2 \partial \theta} \bigg[ \frac{\partial v_e}{\partial \phi} \bigg] + \frac{1}{r^2 \sin^2 \theta} \bigg]$$

#### §B.7 THE DISSIPATION FUNCTION $\Phi v$ FOR NEWTONIAN FLUIDS (SEE EQ. 3.3-3)

Cartesian coordinates (x, y, z):

$$\Phi_{v} = 2\left[\left(\frac{\partial v_{x}}{\partial x}\right)^{2} + \left(\frac{\partial v_{y}}{\partial y}\right)^{2} + \left(\frac{\partial v_{z}}{\partial z}\right)^{2}\right] + \left[\frac{\partial v_{y}}{\partial x} + \frac{\partial v_{x}}{\partial y}\right]^{2} + \left[\frac{\partial v_{z}}{\partial y} + \frac{\partial v_{y}}{\partial z}\right]^{2} + \left[\frac{\partial v_{x}}{\partial z} + \frac{\partial v_{z}}{\partial x}\right]^{2} - \frac{2}{3}\left[\frac{\partial v_{x}}{\partial x} + \frac{\partial v_{y}}{\partial y} + \frac{\partial v_{z}}{\partial z}\right]^{2}$$
(B.7-1)

Cylindrical coordinates  $(r, \theta, z)$ :

$$\Phi_{v} = 2\left[\left(\frac{\partial v_{r}}{\partial r}\right)^{2} + \left(\frac{1}{r}\frac{\partial v_{\theta}}{\partial \theta} + \frac{v_{r}}{r}\right)^{2} + \left(\frac{\partial v_{z}}{\partial z}\right)^{2}\right] + \left[r\frac{\partial}{\partial r}\left(\frac{v_{\theta}}{r}\right) + \frac{1}{r}\frac{\partial v_{r}}{\partial \theta}\right]^{2} + \left[\frac{1}{r}\frac{\partial v_{z}}{\partial \theta} + \frac{\partial v_{\theta}}{\partial z}\right]^{2} + \left[\frac{\partial v_{r}}{\partial z} + \frac{\partial v_{z}}{\partial r}\right]^{2} - \frac{2}{3}\left[\frac{1}{r}\frac{\partial}{\partial r}\left(rv_{r}\right) + \frac{1}{r}\frac{\partial v_{\theta}}{\partial \theta} + \frac{\partial v_{z}}{\partial z}\right]^{2}$$
(B.7-2)

Spherical coordinates  $(r, \theta, \phi)$ :

$$\begin{split} \Phi_{v} &= 2 \left[ \left( \frac{\partial v_{r}}{\partial r} \right)^{2} + \left( \frac{1}{r} \frac{\partial v_{\theta}}{\partial \theta} + \frac{v_{r}}{r} \right)^{2} + \left( \frac{1}{r \sin \theta} \frac{\partial v_{\phi}}{\partial \phi} + \frac{v_{r} + v_{\theta} \cot \theta}{r} \right)^{2} \right] \\ &+ \left[ r \frac{\partial}{\partial r} \left( \frac{v_{\theta}}{r} \right) + \frac{1}{r \partial \theta} \frac{\partial v_{r}}{\partial \theta} \right]^{2} + \left[ \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \left( \frac{v_{\phi}}{\sin \theta} \right) + \frac{1}{r \sin \theta} \frac{\partial v_{\theta}}{\partial \phi} \right]^{2} + \left[ \frac{1}{r \sin \theta} \frac{\partial v_{r}}{\partial \phi} + r \frac{\partial}{\partial r} \left( \frac{v_{\phi}}{r} \right) \right]^{2} \\ &- \frac{2}{3} \left[ \frac{1}{r^{2}} \frac{\partial}{\partial r} \left( r^{2} v_{r} \right) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} \left( v_{\theta} \sin \theta \right) + \frac{1}{r \sin \theta} \frac{\partial v_{\phi}}{\partial \phi} \right]^{2} \end{split}$$
(B.7-3)

## §B.9 THE EQUATION OF ENERGY FOR PURE NEWTONIAN FLUIDS WITH CONSTANT<sup>a</sup> $\rho$ AND k

 $[\rho \hat{C}_{v} DT / Dt = k \nabla^{2} T + \mu \Phi_{v}]$ 

 $\begin{aligned} \frac{Cartesian \ coordinates \ (x, y, z):}{\rho \hat{C}_{p} \left(\frac{\partial T}{\partial t} + v_{x} \frac{\partial T}{\partial x} + v_{y} \frac{\partial T}{\partial y} + v_{z} \frac{\partial T}{\partial z}\right) &= k \left[\frac{\partial^{2} T}{\partial x^{2}} + \frac{\partial^{2} T}{\partial y^{2}} + \frac{\partial^{2} T}{\partial z^{2}}\right] + \mu \Phi_{v} \end{aligned} \tag{B.9-1}^{b} \\ \frac{Cylindrical \ coordinates \ (r, \theta, z):}{\rho \hat{C}_{p} \left(\frac{\partial T}{\partial t} + v_{r} \frac{\partial T}{\partial r} + \frac{v_{\theta}}{r} \frac{\partial T}{\partial \theta} + v_{z} \frac{\partial T}{\partial z}\right) &= k \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r}\right) + \frac{1}{r^{2}} \frac{\partial^{2} T}{\partial \theta^{2}} + \frac{\partial^{2} T}{\partial z^{2}}\right] + \mu \Phi_{v} \end{aligned} \tag{B.9-1}^{b} \\ \frac{Spherical \ coordinates \ (r, \theta, \phi):}{\rho \hat{C}_{p} \left(\frac{\partial T}{\partial t} + v_{r} \frac{\partial T}{\partial r} + \frac{v_{\theta}}{r} \frac{\partial T}{\partial \theta} + \frac{v_{\phi}}{r \sin \theta} \frac{\partial T}{\partial \phi}\right) &= k \left[\frac{1}{r^{2}} \frac{\partial}{\partial r} \left(r^{2} \frac{\partial T}{\partial r}\right) + \frac{1}{r^{2}} \frac{\partial}{\sin \theta} \left(\sin \theta \frac{\partial T}{\partial \theta}\right) + \frac{1}{r^{2}} \frac{\partial^{2} T}{\partial \theta^{2}}\right] + \mu \Phi_{v} \end{aligned} \tag{B.9-2}^{b} \tag{B.9-2}^{b} \end{aligned}$ 

#### §B.11 THE EQUATION OF CONTINUITY FOR SPECIES A IN TERMS OF $ω_A$ FOR CONSTANT<sup>*a*</sup> $ρ D_{AB}$

$$[\rho D\omega_A/Dt = \rho \mathfrak{D}_{AB} \nabla^2 \omega_A + r_A]$$

$$Cartesian \ coordinates \ (x, y, z):$$

$$\rho\left(\frac{\partial \omega_{A}}{\partial t} + v_{x} \frac{\partial \omega_{A}}{\partial x} + v_{y} \frac{\partial \omega_{A}}{\partial y} + v_{z} \frac{\partial \omega_{A}}{\partial z}\right) = \rho \mathfrak{D}_{AB}\left[\frac{\partial^{2} \omega_{A}}{\partial x^{2}} + \frac{\partial^{2} \omega_{A}}{\partial y^{2}} + \frac{\partial^{2} \omega_{A}}{\partial z^{2}}\right] + r_{A}$$

$$Cylindrical \ coordinates \ (r, \theta, z):$$

$$\rho\left(\frac{\partial \omega_{A}}{\partial t} + v_{r} \frac{\partial \omega_{A}}{\partial r} + \frac{v_{\theta}}{r} \frac{\partial \omega_{A}}{\partial \theta} + v_{z} \frac{\partial \omega_{A}}{\partial z}\right) = \rho \mathfrak{D}_{AB}\left[\frac{1}{r} \frac{\partial}{\partial r}\left(r \frac{\partial \omega_{A}}{\partial r}\right) + \frac{1}{r^{2}} \frac{\partial^{2} \omega_{A}}{\partial \theta^{2}} + \frac{\partial^{2} \omega_{A}}{\partial z^{2}}\right] + r_{A}$$

$$(B.11-2)$$

$$Spherical \ coordinates \ (r, \theta, \phi):$$

 $\rho\left(\frac{\partial\omega_{A}}{\partial t}+v_{r}\frac{\partial\omega_{A}}{\partial r}+\frac{v_{\theta}}{r}\frac{\partial\omega_{A}}{\partial\theta}+\frac{v_{\phi}}{r\sin\theta}\frac{\partial\omega_{A}}{\partial\phi}\right)=\rho\mathfrak{D}_{AB}\left[\frac{1}{r^{2}}\frac{\partial}{\partial r}\left(r^{2}\frac{\partial\omega_{A}}{\partial r}\right)+\frac{1}{r^{2}\sin\theta}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial\omega_{A}}{\partial\theta}\right)+\frac{1}{r^{2}\sin^{2}\theta}\frac{\partial^{2}\omega_{A}}{\partial\phi^{2}}\right]+r_{A}$ (B.11-3)

<sup>a</sup> To obtain the corresponding equations in terms of  $x_A$ , make the following replacements:

Replace
$$\rho$$
 $\omega_{\alpha}$  $\mathbf{v}$  $r_{\alpha}$ by $c$  $x_{\alpha}$  $\mathbf{v}^*$  $R_{\alpha} - x_{\alpha} \sum_{\beta=1}^{N} R_{\beta}$ 

## **Open Book (Time: 1 hr)**

Q 1

#### [2+2 = 4]

A solid cylinder of radius R is rotating slowly at constant angular velocity  $\Omega$  in a large body of quiescent fluid. Develop expression for the velocity distributions in the fluid and for the torque T required to maintain the motion.

## Q 2

## [2+1+2 = 5]

The air is blowing at 0.95 mm/s and between two parallel plates of 100 mm length at 300 K and leaving at 310 K. Consider this system as 1D steady state convection diffusion problem of heat transfer. The thermal diffusivity of air is  $19 \text{ mm}^2/\text{s}$ .

- a) Develop the governing energy equation for this system and identify suitable boundary conditions.
- b) Introduce the Peclet Number and non dimensionalise the equation.
- c) Find the temperature profile and estimate the temperature at central position.

## Q 3

## [2+1+2 = 5]

Consider the case of steady state heat conduction in a long slab (*L*) in which heat is generated at a uniform rate of q W/m<sup>3</sup>. The problem can be assumed to be of one dimensional. Both sides of the slab are maintained at  $T = T_{\infty}$ , the temperature of the surrounding fluid, assuming the large heat transfer coefficient.

- a) Develop the governing energy equation with appropriate boundary conditions.
- b) Non dimensionalize the equations and boundary conditions by introducing suitable nondimensional variable
- c) Find out the temperature profile.