

- State and justify any assumptions that you make. Nomenclature should be defined properly.

Q.1 [4*2=8 Marks]

- Prove the theorem: “The eigenvector u^i of a real matrix A corresponding to λ_i is orthogonal to the complex conjugate of every eigenvector v^j of A^t corresponding to an eigenvalue λ_j distinct from λ_i .”
- Integrate $\frac{dy}{dt} = -3y$ with initial value $y_0 = 1$ using $h = 0.025$ upto $t = 0.25$ using explicit Euler technique. Compare with the exact values.
- Calculate the metrics $d_1(u, v)$, $d_2(u, v)$, and $d_\infty(u, v)$ for $u = (1 \ 4 \ 6)^t$ and $v = (1 \ -2 \ 0)^t$
- Express vector $u = (8 \ 10 \ 12)^t$ in \mathbf{R}^3 as a linear combination of basis sets $u^1 = (1 \ 2 \ 3)^t$, $u^2 = (3 \ -3 \ 1)^t$ and $u^3 = (-11 \ -8 \ 9)^t$

Q.2 Using the data given below fit a third-degree polynomial using the Lagrangian interpolation formula.

x	1	3	4	6
y	1	5	15	85

The Lagrangian interpolation formula is given by $y(x) = \sum_{j=0}^n \left[\prod_{\substack{i=0 \\ i \neq j}}^n \frac{(x-x_i)}{(x_j-x_i)} \right] y_j$

[3 Marks]

Q.3 Consider linearly independent set $(2, 0, 1)^t$ $(2, 1, 3)^t$ $(4, 1, 2)^t$ in \mathbf{R}^3 . Generate an orthonormal set using the Gram-Schmidt Orthonormalisation process. **[3 Marks]**

Q.4 Consider the following ODE-IVP

$$\frac{dy_1}{dt} = 9y_1 + 24y_2 + 5 \cos t - \frac{1}{3} \sin t$$

$$\frac{dy_2}{dt} = -24y_1 - 51y_2 - 9 \cos t + \frac{1}{3} \sin t$$

With initial $y_1(0) = 4/3$ and $y_2(0) = 2/3$. Integrate the ODE using the Runge-Kutta algorithm with $h=0.05$ for 1 step. **[3 Marks]**

Fourth order Runge-Kutta algorithm:

$$y_{n+1} = y_n + h \left[\frac{1}{6}k_1 + \frac{1}{3}k_2 + \frac{1}{3}k_3 + \frac{1}{6}k_4 \right]$$

$$k_1 = f[t_n, y_n] \quad k_2 = f \left[t_n + \frac{h}{2}, y_n + \frac{h}{2}k_1 \right] \quad k_3 = f \left[t_n + \frac{h}{2}, y_n + \frac{h}{2}k_2 \right] \quad k_4 = f[t_n + h, y_n + hk_3]$$

Q.5 Determine the heights h_1 , and h_2 in the two-tank network using the eigenvalue method for steady state and transient response. The equations are given by:

$$\frac{dh_1}{dt} = \frac{F_i}{A_1} - \left(\frac{h_1 - h_2}{R_1 A_1} \right)$$

$$\frac{dh_2}{dt} = \left(\frac{h_1 - h_2}{R_1 A_2} \right) - \left(\frac{h_2}{R_2 A_2} \right)$$

Where $F_i/A_1 = 1$, $R_1 A_1 = 0.5$, $R_2 A_2 = 0.5$, $R_1 A_2 = 1$

[8 Marks]

~ALL THE BEST~