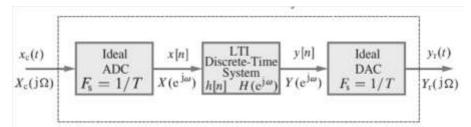
Birla Institute of Technology and Science, Pilani.Comprehensive Examination: EEE F434 : Digital Signal ProcssingMarks: 60AY: 2016-17, Semester: IDate: 14-Dec-2016, WednesdayTime: 180 minutes(OPEN BOOK)Pages: 02

Q1 An analog signal $x_c(t) = 5 \sin(2\pi 250t) + 10 \sin(2\pi 300t)$ is to be processed using the system **15** shown in figure 1.1 in which the sampling frequency is 1 kHz. Design a minimum-order IIR digital filter that will suppress the 300 Hz component down to 20 dB while pass the 250 Hz component with attenuation of 2 dB. Determine the system function of the filter and plot its log-magnitude response in dB. Draw the efficient filter realization structure. Justify.



Q2 A system for the discrete-time spectral analysis of continuous-time signal is shown in figure 2.1. **10**

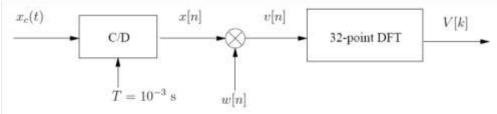


Figure 2.1: Spectral analysis system

w[n] is rectangular window of length 32. $w[n] = \begin{cases} \frac{1}{32} \\ 0 \end{cases}$, $0 \le n \le 31$ otherwise

Listed below are ten signals, at least one of which was the input $x_c(t)$. Indicate which signal(s) could have been the input $x_c(t)$ which produced the plot of |V(k)| shown in dB units in Figure 2.2. As always, provide reasoning for your choice(s). Choice of inputs:

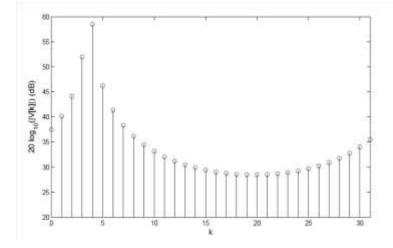


Figure 4.2: Output |V(k)| in dB

- 1. $x_1(t) = 1000 \cos(230\pi t)$
- 2. $x_2(t) = 1000 \cos(115\pi t)$
- 3. $x_3(t) = 10e^{j460\pi t}$

4.
$$x_4(t) = 1000e^{j230\pi t}$$

- 5. $x_5(t) = 10e^{j230\pi t}$
- 6. $x_6(t) = 1000e^{j250\pi t}$
- 7. $x_7(t) = 10\cos(250\pi t)$
- 8. $x_8(t) = 1000 \cos(218.75\pi t);$
- 9. $x_9(t) = 10e^{j200\pi t}$;
- $10. x_{10}(t) = 1000 \cos(230\pi t)$

Q3 The system in figure 3.1 computes an N-point (where N is an even number) DFT X[k] of an N- 10 point sequence x[n] by decomposing x[n] into two N/2-point sequences g1[n] and g2[n], computing the N/2-point DFT's G1[k] and G2[k], and then combining these to form X[k]. If g1[n] is the even-indexed values of x[n] and g2[n] is the odd-indexed values of x[n] i.e. g1[n] = x[2n] and g2[n] = x[2n + 1] then X[k] will be the DFT of x[n].

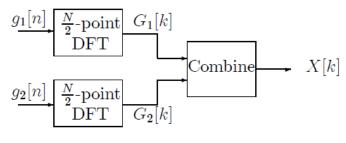


Figure 3.1

In using the system in figure 3.1 an error is made in forming g1[n] and g2[n], such that g1[n] is incorrectly chosen as the odd-indexed values and g2[n] as the even indexed values but G1[k] and G2[k] are still combined as in figure 3.1 and the incorrect sequence [^]X [k] results. Express [^]X [k] in terms of X[k]

Q4 Design a FIR linear-phase, digital filter approximating the ideal frequency response using 15 windowing technique. Plot the magnitude and phase response of filter and advice accordingly.

$$H_d(e^{j\omega}) = \begin{cases} 1, & \text{for } |\omega| \le \frac{\pi}{6} \\ 0, & \text{for } \frac{\pi}{6} \le |\omega| \le \frac{\pi}{3} \\ 1, & \text{for } \frac{\pi}{3} \le |\omega| \le \pi \end{cases}$$

Note: Use minimum 3 (diverse) windows, and 25-tap filter for comparison.

- **Q5** Design a FIR filter that completely blocks the frequency $\omega_c = \frac{\pi}{4}$, by suitable placing poles and **10** zeros in the z-plane. The constructed filter should yield real output given that the input is real.
 - a. Draw poles and zeros of the filter in the z-plane. Clearly state the magnitude and angle.
 - b. Calculate the system function H(z) and frequency response $H(e^{j\omega})$
 - c. Sketch the magnitude response
 - d. If input signal to the filter is given by $x[n] = 10 + 3\cos(\frac{\pi}{4}n) + \sin(\frac{\pi}{3}n + \frac{\pi}{2}), -\infty < n < \infty$. Determine the output y[n] of the filter.